ASNT Fall 2021

Progress in Aircraft and Spacecraft NDT with ET-Arrays

N. Goldfine, T. Dunford, S. Chaplan, J. Nelms, Z. Thomas, A. Washabaugh *Jenteksensors.com*



...Built on Historical
Successes such as for the
Space Shuttle Leading Edge



- MWM-Array Technology Background & Advances
- Currently Funded Transition Programs
 - Bolt-Hole inspection for aircraft (New capability)
 - Surface and buried crack detection away from holes
 - Corrosion imaging for aircraft
 - Weld inspection for spacecraft
 - In-Situ layer-by-layer sensing for Additive
 Manufacturing (New capability)
 - Cold Spray coating characterization
 - Upgrades to engine component inspections

jET® Hand-Held



- 7 Simultaneous Impedance Measurements
- 3 Frequencies Simultaneously
- Supports the MWM and MWM-Array Sensor Technologies
- Weight less than 1 pound
- Best of class impedance measurement



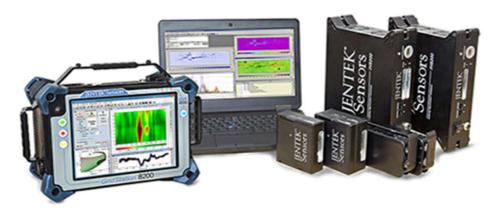




Near Surface MWM-Array

7-Channel MWM & MWM-Arrays

GridStation® GS8200



- Standard 19 and 39 Channel Systems standard
- Stackable up to 119 Channels
- 3 frequencies simultaneously
- All channel impedances and real and imaginary parts (or mag. & phase) recorded simultaneously
- Support for both inductive and magnetoresistive (MR) sensing element arrays



39-Channel MWM-Array

jET® Hand-Held



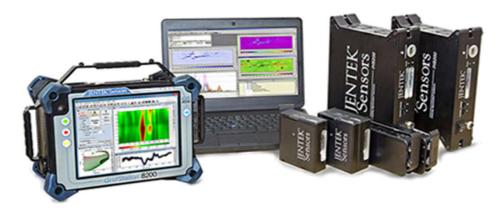
Available Upgrades

- 7-Channel 5 ft. flexible extension cable
- Data access at all levels for 3rd party development
- Improved intelligent filtering and signature libraries
- Improved user interface with tabs and automated reporting

Planned Upgrades

- New D2P2 SBIR for field hardened solution and bolt-hole inspection
- Integrated larger touch screen
- Improved battery pack

GridStation® GS8200



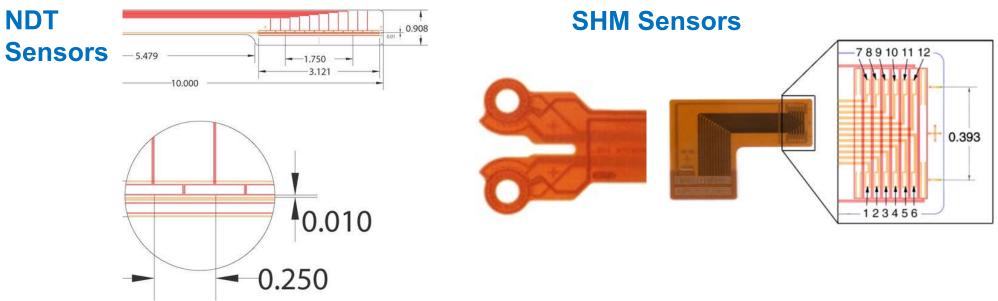
Available Upgrades

- 39- Ch 5 ft. flexible extension cable
- Data access at all levels for 3rd party development
- Improved intelligent filtering and signature libraries
- Improved user interface with tabs and automated reporting

Planned Upgrades

- New Phase 2.5 SBIR to develop "backpack portable" unit
- Improved battery pack
- 79 and 119 Channel commercial systems

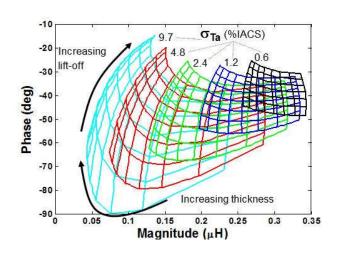
unique approach to sensor design first eliminates unmodeled behavior to empower physics model based data analytics



- MWM-Arrays input a current through a unique single or dual rectangle drive construct to produce a time varying magnetic filed at up to three frequencies simultaneously, and measure voltage at a linear array of sensing elements to provide imaging of material conditions and detection of defects
- Simultaneous measurement at neighboring channels (and for both the real and imaginary parts, or magnitude and phase, of the impedance) enables both high speed scanning and intelligent filtering

Multiple Simultaneous Property Measurement: Using Model-**Based Multivariate Inverse Methods**

- Rapid conversion of sensor data into material properties
 - Electrical conductivity
 - Magnetic Permeability
 - Layer Thickness
 - Intelligent filtering with signature libraries for defect detection and sizing



Intelligent Filtering: Using Spatial and Temporal Signatures and Signature Libraries

- Rapid conversion of material property data at multiple sensing elements to defect responses (including sizing) with reduced false indications
 - Crack detection and sizing
 - Corrosion imaging and sizing for multiple layered constructs
 - Geometric feature estimation and accommodation
 - Signature library training and management for rapid data analysis and portability to new applications
 - Targeted anomaly suppression for reduced false indications and improved signal-to-noise performance

Ease of Use: (ASTM E2338; ASTM E2884)

- Air and Reference Calibration to reduce burden on inspectors and improve reliability
- Intuitive Digital Data Visualization Tools - to empower customers and decision makers
- Immediate Calibration and Inspection Performance Verification - to build confidence and reduce uncertainty
- Targeted user interfaces for large ongoing transition opportunities:
 - > Bolt-Hole Inspection
 - > Gun Barrel Inspection
 - > Aircraft Corrosion Imaging
 - > Pipeline and Riser Inspection
 - ➤ Land-Based Turbine Inspection
 - > In-Process Sensing for AM (Additive Manufacturing)

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Picking the Right MWM-Array Sensor (Depth of Penetration is NOT Depth of Sensitivity)

Field Variation with Depth ≈

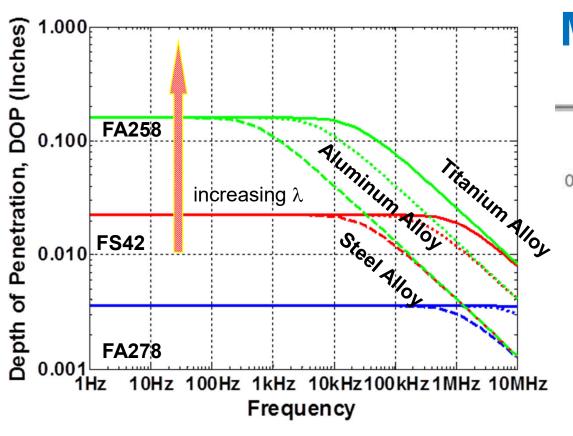
$$e^{-\Gamma_n z}$$

Spatial Fourier Mode Depth of Penetration = $1/Re(G_n)$

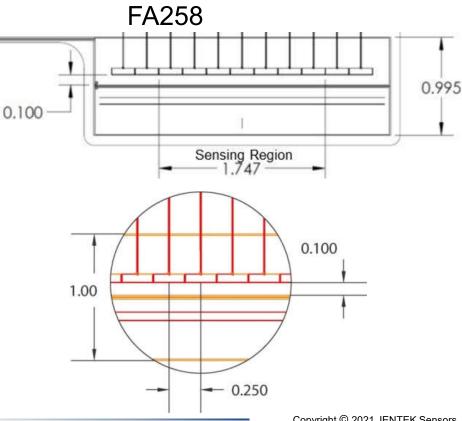
Low frequency asymptote = $\lambda/2\pi$

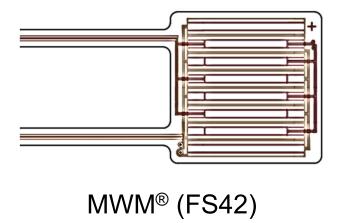
$$\Gamma_{\rm n} = \sqrt{(2\pi n/\lambda)^2 + j2/\delta^2}$$

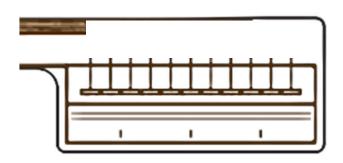
Skin depth: $\delta = \sqrt{\frac{1}{\pi f \mu \sigma}}$



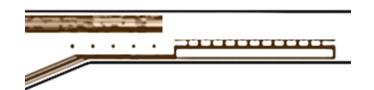
MWM®-Array



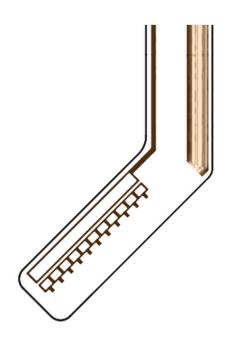




MWM®-Array (FA296) Dual Rectangle Drive



MWM®-Array (FA260) Sense Elements Outside Drive



MWM®-Array (FA314) for Bolt Hole (Older version than FA318 currently in use)

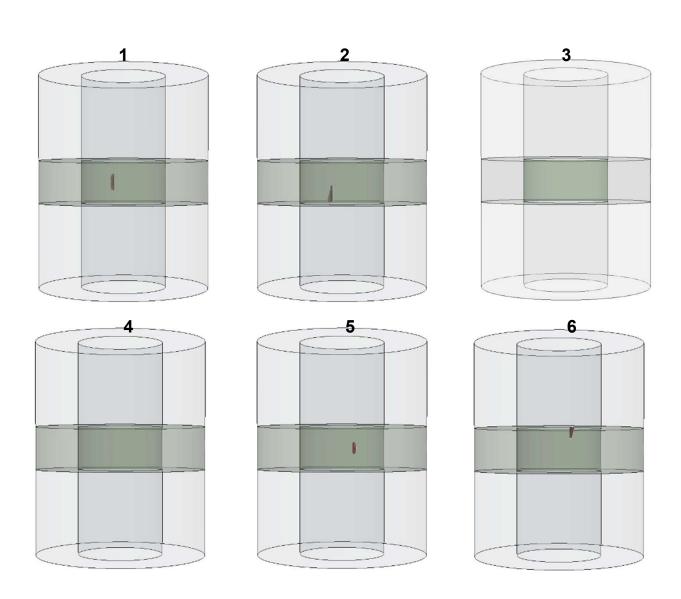
- Bolt-Hole inspection for aircraft
- Surface and buried crack detection for structures and engines
- > Corrosion imaging for aircraft
- Weld inspection for spacecraft
- In-Situ layer-by-layer sensing for Additive Manufacturing
- Cold Spray coating characterization
- Upgrades to engine component inspections

Prototype jET Handheld Scanner for Bolt-Hole Inspection

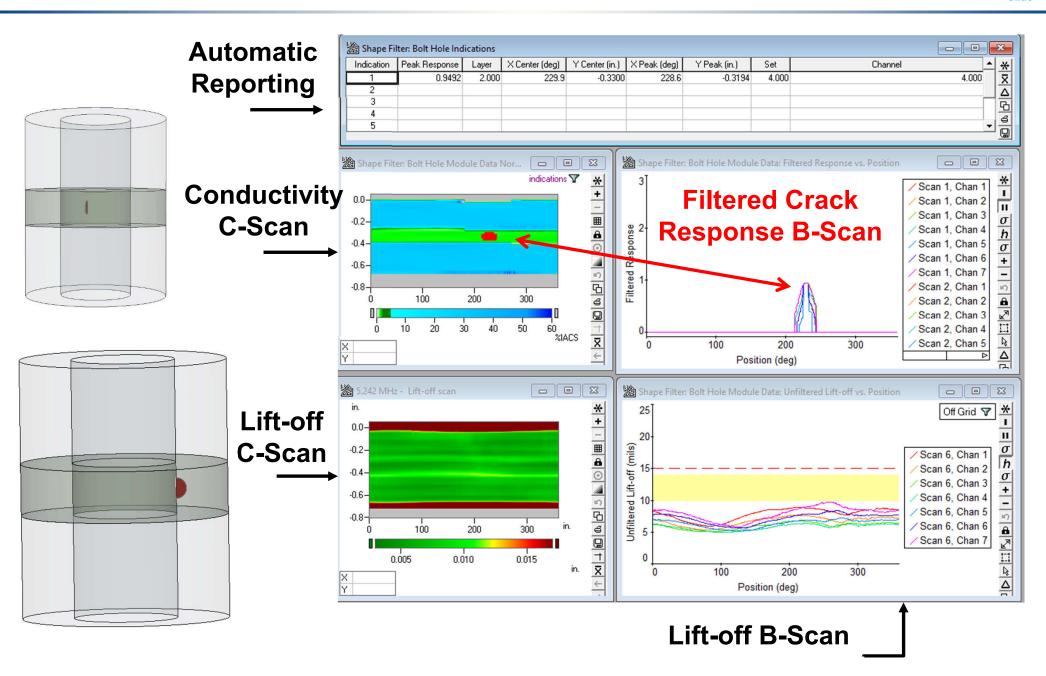
- Current prototype of "wrapping-lead" bolt hole scanner
- A new more compact version is under development with an alternative internal configuration
- 5 ft. flexible lead enables more convenient scanning
- GridStation software performs multi-variate inverse methods and intelligent filtering



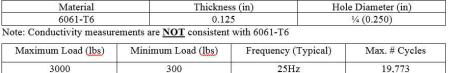
- Corner EDM notches
- Mid-wall EDM notches
- Real crack samples can be inserted in material stack-ups



Example Result: 3 Layer Stack-up

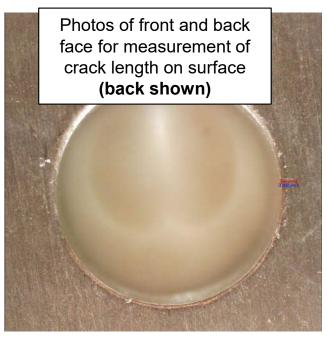


Real Crack Specimen Fabrication

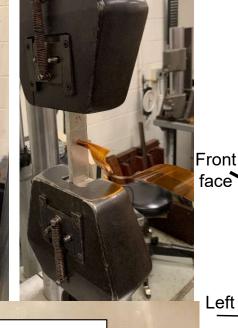


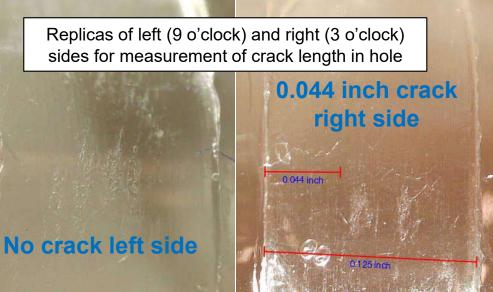
Left		Right	
Length in Hole (in)	Length on Surface (in)	Length in Hole (in)	Length on Surface (in)
0.000	0.000	0.044	0.018
1.310 MHz - Co	nductivity vs. Set	1.310 MHz - L	Lift-off vs. Set
-		50	

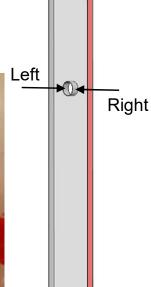
Sample 1









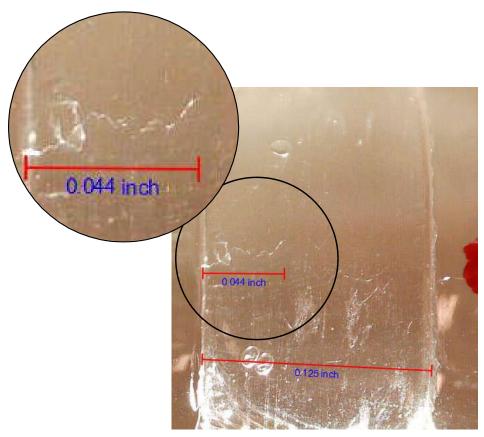


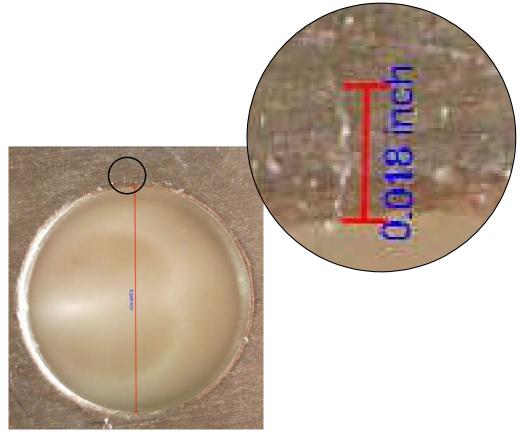
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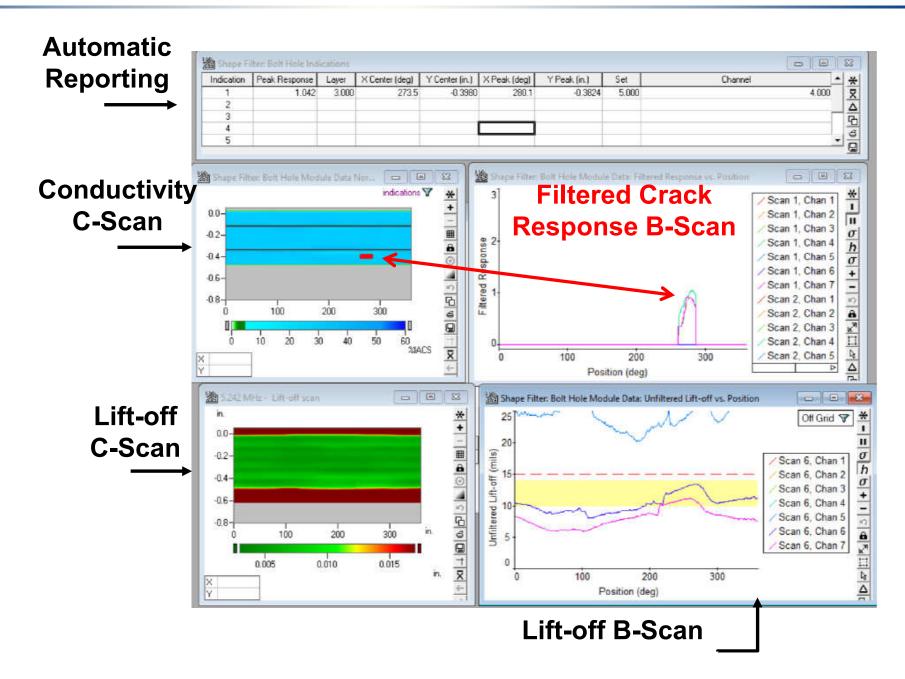
Real Crack Specimen 1

- ¼ in. hole; Al alloy
- · Left inside: No defect
- Right inside: 0.044 in. corner crack
 (0.018 in. external surface crack)

Right Side



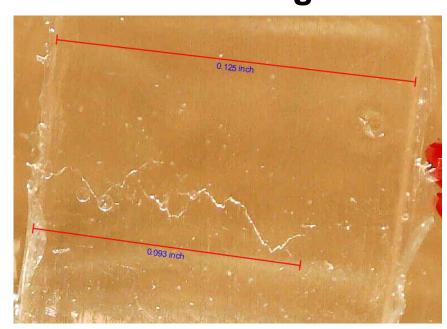


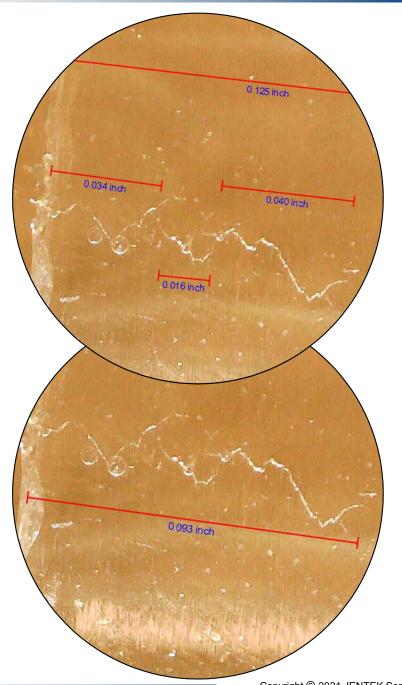


Real Crack Specimen 2

- ¼ in. hole; Al alloy
- Left inside: No defect
- Right inside: 0.093 in. crack near edge (no external surface crack visible)
- Appears to be three nearly coalesced cracks of lengths 0.040 in., 0.016 in., and 0.034 in.

 Right Side

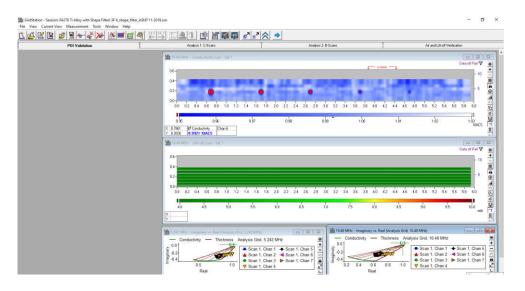




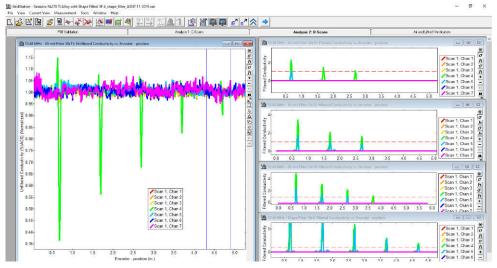
Surface Crack Detection Interface for POD verification and Inspection



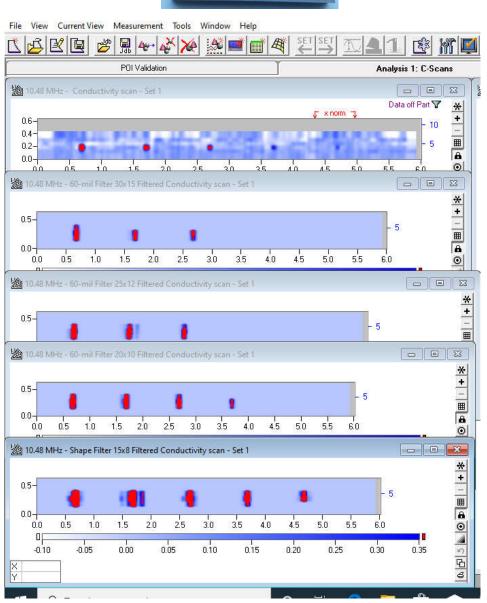
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Liftoff & coverage verification

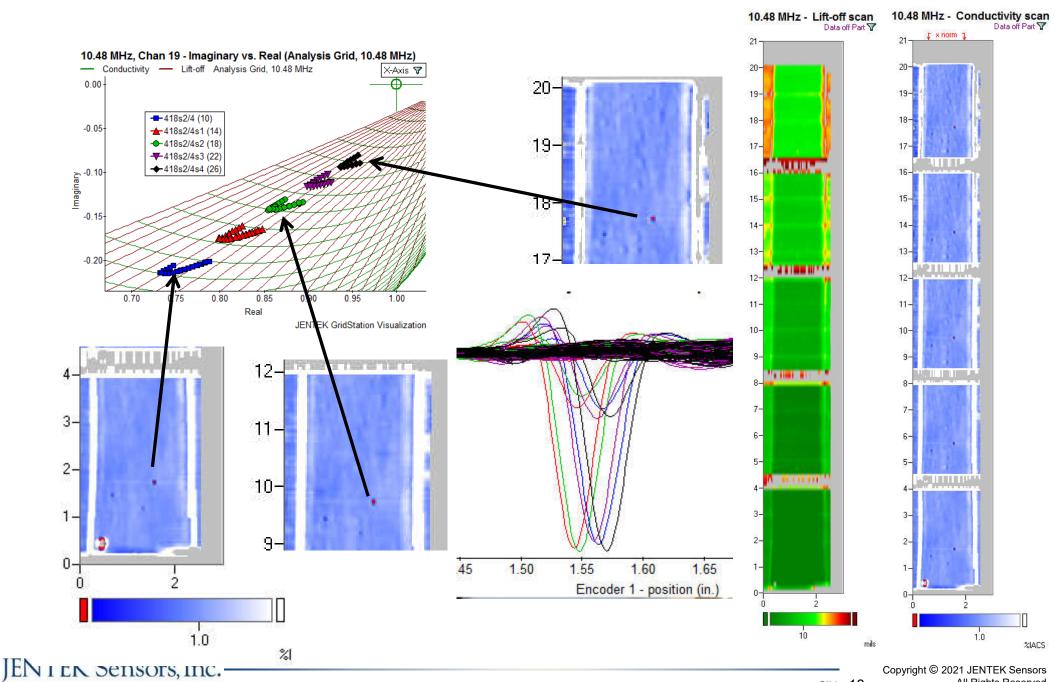


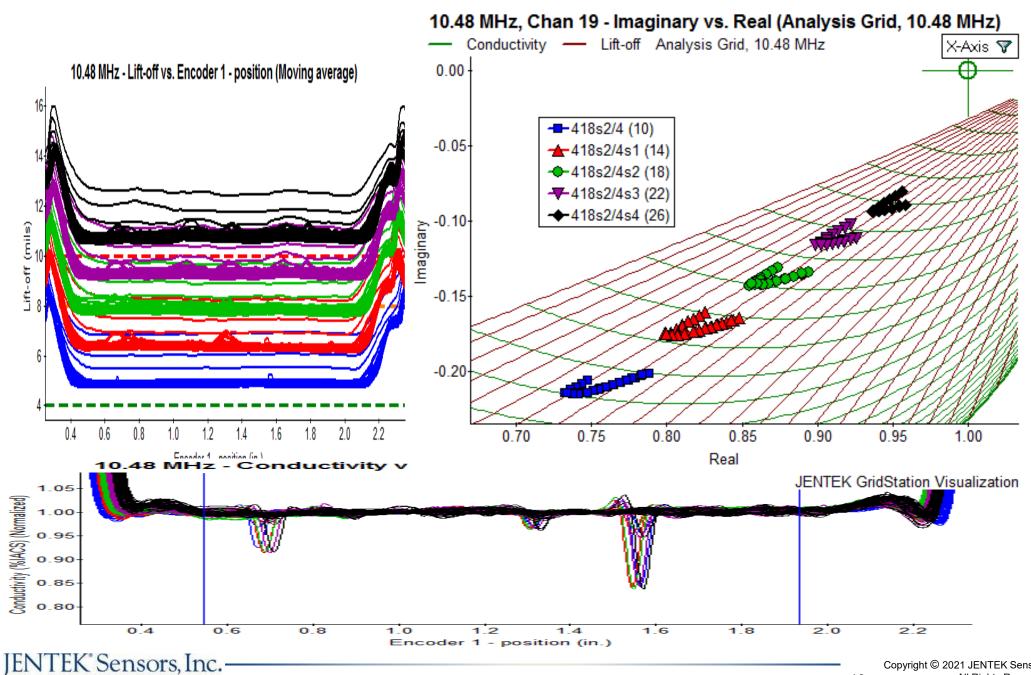
Unfiltered and Filtered B-Scans



Unfiltered and Filtered C-Scans

Surface Cracks: Rescaling of Conductivity Response

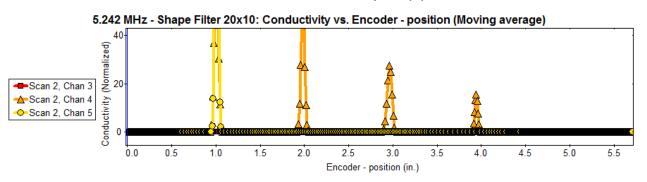




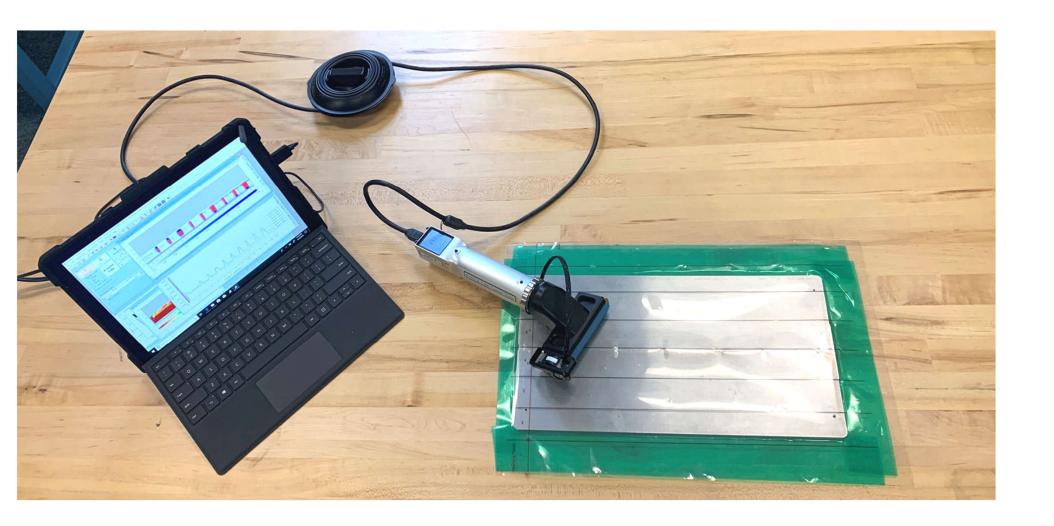
Slide 19

Titanium Alloy Unfiltered and Shape Filtered Results

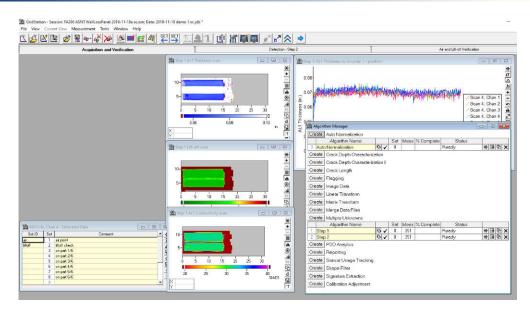
EDM Notch Sizes: 0.06 0.04 0.03 0.02 length 0.015 x0.03 x0.02 x0.015 x0.01 x0.0075 depth 10.48 MHz - Conductivity vs. Encoder - position (Moving average) (Normalized) 0.9 Lift-Off 50 🐨 Scan 2, Chan 3 Scan 2, Chan 4 Scan 2, Chan 5 4.0 0.5 1.0 1.5 2.0 2.5 3.0 3.5 4.5 5.0 5.5 Encoder - position (in.) 5.242 MHz - Shape Filter 15x8: Conductivity vs. Encoder - position (Moving average) malized) Scan 2, Chan 3 Scan 2, Chan 4 Conductivity Scan 2, Chan 5 2.0 0.0 0.5 1.0 1.5 2.5 3.0 3.5 4.0 4.5 5.0 5.5 Encoder - position (in.)



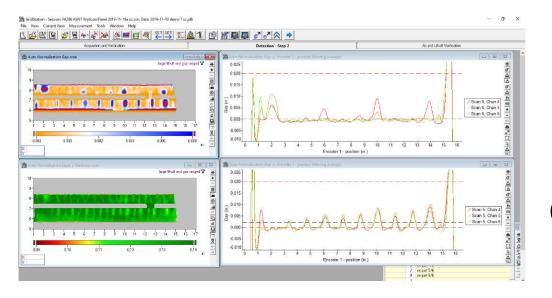
I.6: Corrosion Imaging Performance Study Ongoing

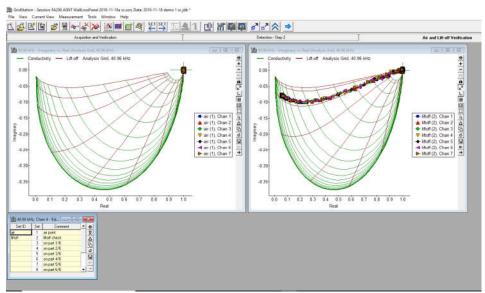


I.6: Corrosion Loss Imaging and POI Verification



Liftoff & coverage verification



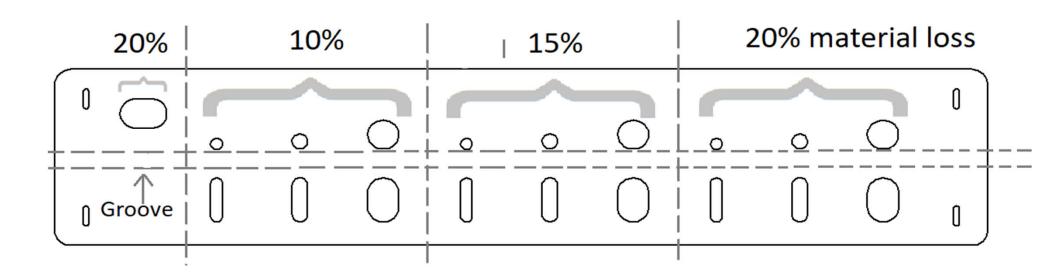


Air Calibration & Cal Check (Air and liftoff)

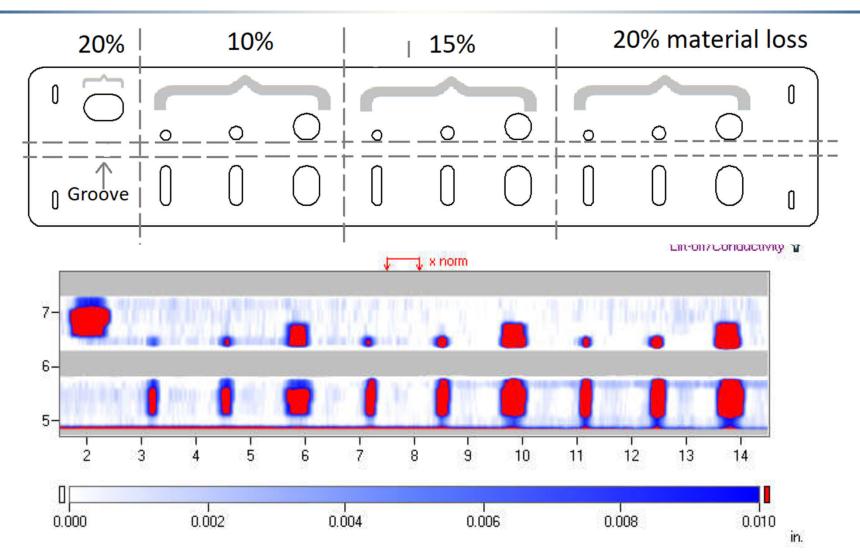
C-Scan and B-Scan data visualizations

I.6: 15 inch Corrosion Loss Sample



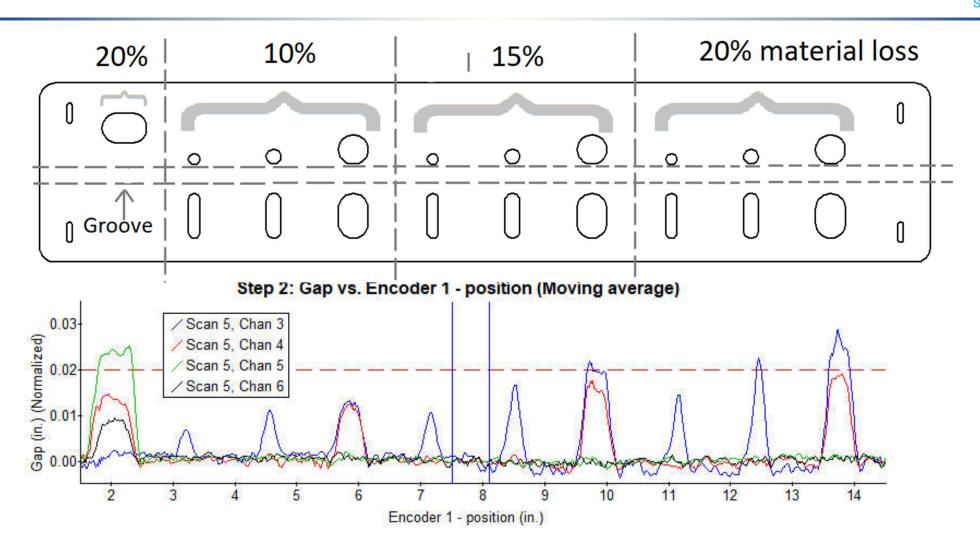


I.6: FA296: 15 inch Corrosion Loss Sample (1)



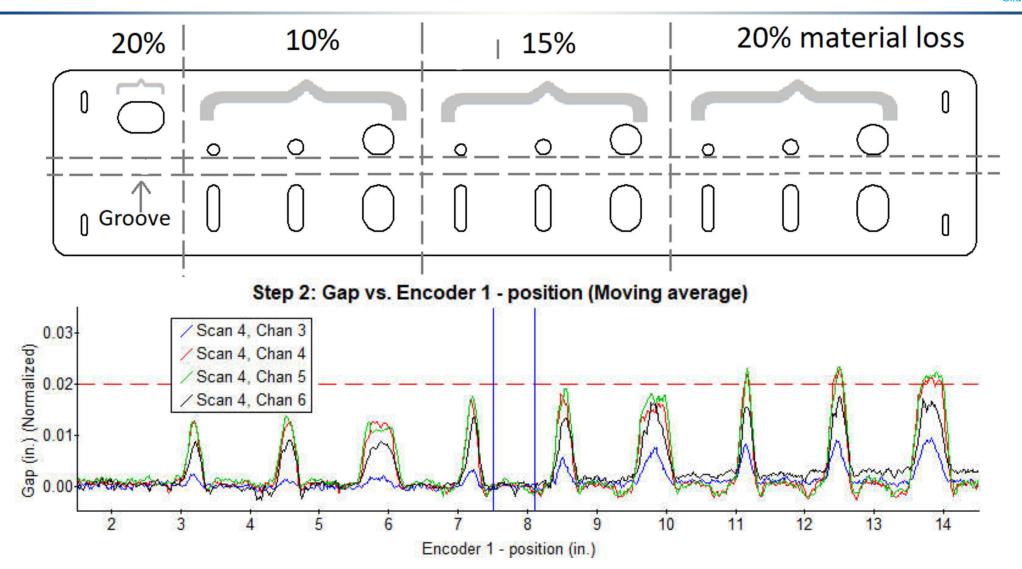
Filtered and normalized C-scan of Gap data across the corrosion defect locations.

I.6: FA296: 15 inch Corrosion Loss Sample Holes (2)



Normalized B-scan of Gap data across the flat bottom hole defect locations.

I.6: FA296: 15 inch Corrosion Loss Sample Slots (3)6



Normalized B-scan of Gap data across the flat bottom slot defect locations.

Currently Funded Transition Programs (continued)

- Weld inspection for spacecraft
 - Friction Stir Welds
 - POD studies completed at scan speeds up to 10 in./second
 - Replacement for LPI
 - Volumetric Weld Inspection
 - For complex geometries
 - Surface and buried defects
 - Enhanced Portability of GS8200 ("Backpack Portable")

Currently Funded Transition Programs (continued)

- In-Situ layer-by-layer sensing for Additive Manufacturing
 - Two customer funded initiatives ongoing (LPBF, DED)
 - Fully integrated pilot line testing planned for 2022
- Cold Spray coating characterization
 - Production qualification completed for one application
 - Sustainment application development ongoign
- Upgrades to engine component inspections
 - jET validation ongoing for propeller cold work upgrade
 - GS8200 upgrade pending for disk slot inspections

- Substantial upgrades are ongoing to the MWM-Array for depot/production, field and embedded applications
- Currently Funded Transition Programs include
 - Bolt-Hole inspection for aircraft (New capability)
 - Surface and buried crack detection away from holes
 - Corrosion imaging for aircraft
 - Weld inspection for spacecraft
 - In-Situ layer-by-layer sensing for Additive
 Manufacturing (New capability)
 - Cold Spray coating characterization
 - Upgrades to engine component inspections